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Abbreviations

LRF	Line Following Robot
PID	Proportional Integral Derivative
DC	Direct Current
AC	Alternation Current
PM	Permanent Magnet
PWM	Pulse Width Modulation
EMF	Electro Motive Force
KP	Proportional Gain
kI	Integral Gain
kD	Derivative Gain
NSS	Non-Steady State
IDE	Integrated Development Environment
MVS	Microsoft Visual Studio
ADC	Analog to Digital Convert
ISP	In System Programmable
CDS	Cadmium Supplied
LDR	Light Dependent Resistor
UART	Universal Asynchronous Receiver/Transmitter
ALU	Arithmetic Logic Unit
