



بِسْمِ اللَّهِ الرَّحْمَنِ الرَّحِيمِ

Sudan University of Science and Technology
College of Graduate Studies



TRAJECTORY TRACKING CONTROLLER FOR WHEELED MOBILE ROBOT

متحكمة تتبع المسار للروبوت المتحرك بعجلات

A Thesis Submitted in Partial Fulfillment of the Requirements for the Degree of
Master of Science in Electrical Engineering (Microprocessors and Control)

Submitted By:

Walied Mohamed Elfatih Mahgoub Abdalla

Under Supervision of:

Dr .Ibrahim Mohamed Hafiz Sanhoury

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