

Solution of A fractional Differential Equation Based on Hilfer's Derivative Operator

Maher Y. K. Hamada^{1*}, Shawgy Hussein², Mohsen Hassan Abdallah³

*1-Palestine Technical College, Dair Al-Balah, Gaza-Palestine. Email:maherhamada@hotmail.com

2-Department of Mathematics - College of Science, Sudan University of Science and Technology, Sudan.

3- Department of Mathematics, Faculty of mathematical Sciences, Khartoum University, Sudan.

ABSTRACT

In this paper, the solution of the fractional differential equation $x(D_{0^+}^{u,v} y)(x) = \lambda(\mathcal{E}_{\alpha,\beta,pw,0^+}^{\gamma,\delta,q})(x)$

with the initial condition $(I_{0^+}^{(1-v)(1-u)} y)(0_+) = c_1$ was investigated, based on the Hilfer's fractional derivative.

المستخلص

في هذه الورقة تمت مناقشة حل المعادلة التفاضلية الكسرية $x(D_{0^+}^{u,v} y)(x) = \lambda(\mathcal{E}_{\alpha,\beta,pw,0^+}^{\gamma,\delta,q})(x)$ طبقاً للشروط الابتدائية $y(0_+) = c_1$ المعتمدة على المشتق الكسرية لهيلفر.

KEYWORDS: Fractional differential equation, Hilfer derivative operator, Mittag-Leffler function, Fractional calculus, Laplace convolution theorem.

INTRODUCTION

Mittag-Leffler function has been studied in the early 1900s⁽¹⁻³⁾, its importance is realized during the last two decades due to its involvement in problems of physics, chemistry and applied science. Further properties of generalization of Mittag-Leffler function associated with fractional calculus operators have been studied⁽⁴⁻⁶⁾.

Kilbas made relevant references to analytical solution of initial and boundary value problems associated with fractional differential equations⁽⁷⁾, one of them is Cauchy type problem

$$(D_{a^+}^\lambda y)(x) = \lambda(\mathcal{E}_{\alpha,\beta,w,a^+}^{\lambda,1})(x) + f(x) \quad (1)$$

with the initial condition $(D_{a^+}^{\lambda-k} y)(0_+) = b_k$.

The homogeneous differential equation corresponding to (1) when $f(x)=0$ is a generalization of a certain first-order Volterra-type integral differential equation governing the unsaturated behavior of free electron laser^(3,8).

Hence by using Laplace transform method⁽⁹⁾, an explicit solution on $L(0,\infty)$ of a more complicated fractional differential equation than (1) can be given which contains the generalized Riemann-Liouville fractional derivative operator,⁽¹⁰⁻¹³⁾

$$D^\mu f(x) = D^m [D^{-\nu} f(x)] \quad \mu, t > 0, \quad \nu = m - \mu > 0$$

The following definitions were used in this study,

Definition (1):-

(i)- Hilfer's fractional derivative⁽³⁾ is defined as:

$$(D_{a^+}^{u,v} \varphi)(x) = \left[I_{a^+}^{v(1-u)} \frac{d}{dx} \left(I_{a^+}^{(1-u)(1-v)} \varphi \right) \right](x)$$

and its Laplace transformation ⁽⁹⁾ is given by

$$L(D_{0^+}^{u,v} \varphi)(s) = s^u L[\varphi(x)](s) - s^{v(1-u)} \left(I_{0^+}^{(1-v)(1-u)} \varphi(x) \right)(0_+) \quad ; \quad 0 < u < 1, \quad 0 \leq v \leq 1, \quad \gamma, \alpha, \beta, w \in C,$$

(ii)- An integral operator ^(13,14) is defined as

$$(\mathcal{E}_{\alpha, \beta, w, a^+}^{\gamma, \delta, q} \varphi)(x) = \int_0^x (x-t)^{\beta-1} E_{\alpha, \beta, p}^{\gamma, \delta, q} [w(x-t)^\alpha] \varphi(t) dt$$

(iii)- First order differential equation ^(15- 17) $y' + p(x)y = Q(x)$ has the solution

$$y(x) = e^{- \int p(x) dx} \left[c_2 + \int Q(x) e^{\int p(x) dx} dx \right]$$

(iv)- Laplace transformation is given by ⁽⁹⁾

$$L\left[z^{\alpha-1} E_{\alpha, \beta, p}^{\gamma, \delta, q}(xz^\sigma) ; s\right] = \frac{\overline{\delta s}^{-\alpha}}{\overline{\gamma}} {}_3\psi_2 \left[\begin{matrix} (\gamma, q), (\alpha, \sigma), (1, 1) \\ (\beta, \alpha), (\delta, \sigma) \end{matrix} ; \frac{x}{s^\sigma} \right]$$

(v)- Also another Laplace transformation see ^(7,18-20) is given by

$$L\left\{ \frac{1}{u} \int_0^t t^{\mu-1} (x-t)^{\beta-1} E_{\alpha, \beta, p}^{\gamma, \delta, q} [w(x-t)^\alpha] dt ; s \right\} = \frac{1}{s^\mu} \sum_{n=0}^{\infty} \frac{(\mathcal{Y}_{qn})^n}{(\delta_{pn})(\alpha+\beta)} s^{\alpha n + \beta}$$

(vi)- The two -parameter function of Mittag-Leffler ⁽¹⁻³⁾ is defined by

$$E_{\alpha, \beta}(z) = \sum_{k=0}^{\infty} \frac{z^k}{\alpha k + \beta} \quad \alpha > 0 \quad \beta > 0$$

(vii)- Generalized Mittag-leffler function ⁽¹⁻³⁾ defined as

$$E_{\alpha, \beta, p}^{\gamma, \delta, q}(z) = \sum_{n=0}^{\infty} \frac{(\mathcal{Y}_{qn}) z^n}{(\alpha n + \beta)(\delta)_{pn}}$$

We need the theorem proved by ⁽¹⁸⁾

Theorem (2):-

In the space $L(0, \infty)$ if the fractional differential equation is considered

$$(D_{0^+}^{u,v} y)(x) = \lambda (\mathcal{E}_{\alpha, \beta, p, w, 0^+}^{\gamma, \delta, q})(x) + f(x)$$

with $\min \{ \operatorname{Re}(\alpha), \operatorname{Re}(\beta), \operatorname{Re}(\gamma), \operatorname{Re}(\delta) \} > 0$ and $p, q > 0$, and with initial condition

$(I_{0^+}^{(1-v)(1-u)} \varphi)(0_+) = c$, then we have the solution

$$\begin{aligned} y(x) &= c \frac{x^{u-v(1-u)-1}}{u-v+uv} + \lambda x^{\beta+u} E_{\alpha, \beta+u+1, p}^{\gamma, \delta, q}(wx^\alpha) \\ &\quad + \frac{1}{u} \int_0^x (x-t)^{u-1} \varphi(t) dt \end{aligned} \quad (3)$$

Proof:-

Using Definition (1) (i) and (ii), also making use of (iv) we can get

$$L(D_{0^+}^{u,v} (y)) = L\left[\lambda (\mathcal{E}_{\alpha, \beta, p, w, 0^+}^{\gamma, \delta, q})(x) + L(f(x)) \right]$$

Hence

$$\begin{aligned} s^u L(y) - s^{v(1-u)} \left(I_{0^+}^{(1-v)(1-u)} (y) \right)(0_+) &= \\ \lambda L\left[\int_0^x (x-t)^{\beta-1} E_{\alpha, \beta, p}^{\gamma, \delta, q} (x-t)^\alpha dt \right] + L(f(x)) & \end{aligned}$$

According to Laplace convolution theorem and by applying the initial condition we have

$$s^u Y(s) - c s^{v(1-u)} = \lambda L\left[x^{\beta-1} E_{\alpha, \beta, p}^{\gamma, \delta, q}(wx^\alpha) \right](s) + L(I)(s) + F(s)$$

$$= \frac{\lambda s^{-\beta} \overline{\delta}}{\overline{\gamma}} {}_3\psi_2 \left[\begin{matrix} (\gamma, q), (\beta, \alpha), (1, 1) \\ (\beta, \alpha), (\delta, p) \end{matrix} ; \frac{w}{s^\alpha} \right] \frac{1}{s} + F(s)$$

$$= \frac{\lambda s^{-\beta-1} \overline{\delta}}{\overline{\gamma}} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix} ; \frac{w}{s^\alpha} \right] + F(s).$$

Divided the above equation by s^u we get

$$Y(s) = c s^{\beta-u} + \frac{\lambda^{-\beta-u}}{\gamma} \sum_{n=0}^{\infty} \frac{(\gamma+qn)(1+n)}{(1+\delta+pn)n!} \left(\frac{w}{s^\alpha} \right) + s^{-u} F(s).$$

Taking Laplace inverse of both sides of the last equation, we get

$$\begin{aligned} y(x) &= c L[s^{\beta-u}] (x) + \frac{\lambda}{\gamma} \sum_{n=0}^{\infty} \frac{(\gamma+qn)(1+n)}{n! (\delta+pn)} w^n L[s^{-\alpha-\beta-u}] \\ &\quad + L \left[\frac{x^{u-1}}{u} f(x) \right], \end{aligned}$$

where

$$s^{-u} F(s) = L \left(\frac{x^{u-1}}{u} f(x) \right).$$

Again applying Laplace convolution theorem, we get

$$\begin{aligned} y(x) &= c \frac{x^{u-v(1-u)}}{u-v+uv} + \lambda x^{\beta+u} E_{\alpha,\beta+u+1,p}^{\gamma,\delta,q} (wx^\alpha) \\ &\quad + \frac{1}{u} \int_0^x (x-t)^{u-1} f(t) dt, \end{aligned}$$

which gives the solution.

Remark (3):

If we put $f(t) = t^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wt^\alpha)$ in (2) we get the following particular case of (3) which is stated in the next lemma.

Lemma (4):

Under the same conditions of theorem (2), the following fractional differential equation

$$(D_{0^+}^{u,v} y)(x) = \lambda (\mathcal{E}_{\alpha,\beta,pw,0^+}^{\gamma,\delta,q}) (x) + x^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wx^\alpha),$$

with the initial condition $(I_{0^+}^{(1-v)(1-u)} \varphi) = c$ has the solution

$$y(x) = c \frac{x^{u-v(1-u)}}{(u-v(1-u))} + (\lambda+1) E_{\alpha,\beta+u+1,p}^{\gamma,\delta,q} (wx^\alpha).$$

Proof:-

Putting $f(x) = x^\beta E_{\alpha,\beta+u+1,p}^{\gamma,\delta,q} (wx^\alpha)$ in (3) we get

$$\begin{aligned} y(x) &= c \frac{x^{u-v(1-u)-1}}{u-v+uv} + \lambda x^{\beta+u} E_{\alpha,\beta+u+1,p}^{\gamma,\delta,q} (wx^\alpha) \\ &\quad + \frac{1}{u} \int_0^x (x-t)^{u-1} t^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wt^\alpha) dt. \end{aligned}$$

But

$$\begin{aligned} &\frac{1}{u} \int_0^x (x-t)^{u-1} t^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wt^\alpha) dt = \\ &L^{-1} L \left[\frac{1}{u} \int_0^x (x-t)^{u-1} t^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wt^\alpha) dt \right] \\ &= L^{-1} \left\{ L \left(\frac{x^{u-1}}{u} \right) (s) L(x^{\beta+1-1} E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wx^\alpha))(s) \right\}. \end{aligned}$$

From Definition (1) (iv) we get

$$\begin{aligned} &\frac{1}{u} \int_0^x (x-t)^{u-1} t^\beta E_{\alpha,\beta+1,p}^{\gamma,\delta,q} (wt^\alpha) dt \\ &= L^{-1} \left\{ \frac{1}{s^u} \frac{\overline{\delta}}{\gamma} s^{-\beta-1} {}_3\psi_2 \left[\begin{matrix} (\gamma, q), (\beta+1, \alpha), (1, 1) \\ (\beta+1), (\delta, p) \end{matrix}; \frac{w}{s^\alpha} \right] \right\} (s) \end{aligned}$$

$$= L^{-1} \left\{ \frac{\overline{\delta}}{\gamma} \sum_{n=0}^{\infty} \frac{\frac{1}{n!} (\gamma+qn)(1+n)}{(\delta+pn)(4)} \left(\frac{w}{s^\alpha} \right)^n s^{u-\beta-1} \right\} (x) \quad (4)$$

$$= \sum_{n=0}^{\infty} \frac{(\gamma)_{qn}}{(\delta)_{pn}} w^n L^{-1} \left\{ s^{-\alpha n - \beta - u - 1} \right\} (x)$$

$$= \sum_{n=0}^{\infty} \frac{(\gamma)_{qn}}{(\delta)_{pn}} w^n \frac{s^{(\alpha n + \beta + u + 1)}}{(x^n)(\alpha n + \beta + u + 1)}$$

$$= x^{\beta + u} E_{\alpha, \beta + u + 1, p}^{\gamma, \delta, q} (wx^{-\alpha}),$$

by applying Laplace's convolution theorem.
Hence the solution is given by

$$y(x) = c \frac{x^{u-v(1-u)-1}}{(u-v(1-u))} +$$

$$(\lambda + 1) E_{\alpha, \beta + u + 1, p}^{\gamma, \delta, q} (wx^{-\alpha}). \quad (5)$$

RESULTS

Now we give our main results

Theorem (5):

Under the same conditions of Theorem (2), the following fractional differential equation

$$x(D_0^{u,v} y)(x) =$$

$$\lambda (\varepsilon_{\alpha, \beta, pw, 0^+}^{\gamma, \delta, q})(x) \quad (6)$$

with the initial condition $(I_0^{(1-v)(1-u)} y)(0_+) = c_1$ has the following solution

$$y(x) = c_2 \frac{x^{u-1}}{u} + c_1 \frac{x^{u-v(1-u)-1}}{(u-v(1-u))} + \lambda \int_0^x t^{u-1} (x-t)^{\beta-1} E_{\alpha, \beta+1, p}^{\gamma, \delta, q} w(w-t)^\alpha dt \quad (7)$$

where c_1, c_2 are constants.

Proof:

We will use the same procedures as in Theorem (2) in addition, we can use

$$\frac{\partial^n}{ds^n} [Ly(x)](s) = (-1)^n L[x^n y(x)](s) \quad (8)$$

Now take the Laplace transform for both sides of eqn. (6)

$$L[x(D_0^{u,v} y)](s) = \lambda L[\varepsilon_{\alpha, \beta, pw, 0^+}^{\gamma, \delta, q}](s).$$

Now using (8) with $n=1$ we get

$$\frac{\partial}{\partial s} [L(D_0^{u,v} y)](s) = (-1)L[xD_0^{u,v} y](s)$$

From definition (1) (i) and theorem (2), we have

$$\frac{\partial}{\partial s} [s^u Y(s) - c_1 s^{v(1-u)}] = -\lambda \frac{s^{-\beta-1} \bar{\delta}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (\beta, \alpha), (1, 1) \\ (\delta, p), (\beta, \alpha) \end{matrix}; \frac{w}{s^\alpha} \right]$$

$$s^u Y'(s) - us^{u-1} Y(s) - c_1 v(1-u) s^{v(1-u)-1} +$$

$$\lambda \frac{s^{-\beta-1} \bar{\delta}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix}; \frac{w}{s^\alpha} \right] = 0$$

Dividing the above equation by s^u , yields

$$Y(s) - \frac{u}{s} Y(s) - c_1 v(1-u) s^{v(1-u)-u-1} + \lambda \frac{s^{-\beta-u-1} \bar{\delta}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix}; \frac{w}{s^\alpha} \right] = 0 \quad (9)$$

Which is a first order ordinary differential equation then, the solution of (9) is

$$Y(s) = \exp \left(- \int \frac{u}{s} ds \right) \times \left[c_2 + \left(\int \lambda \frac{s^{-\beta-u-1} \bar{\delta}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix}; \frac{w}{s^\alpha} \right] ds \right) \right]$$

So that

$$Y(s) = s^{-u} \left[c_2 + \left(c_1 \int v(1-u) s^{v(1-u)-u-1} - \lambda \frac{s^{-\beta-u-1} \bar{\delta}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix}; \frac{w}{s^\alpha} \right] \right) s^u ds \right]$$

$$\begin{aligned}
 &= s^{-u} \left[c_2 + \left(c_1 \int v(1-u) s^{v(1-u)-1} - \lambda \frac{s^{-\beta-1}}{\gamma} {}_2\psi_1 \left[\begin{matrix} (\gamma, q), (1, 1) \\ (\delta, p) \end{matrix} ; \frac{w}{s^\alpha} \right] ds \right) \right] \\
 &= s^{-u} \left[c_2 + c_1 \frac{v(1-u) s^{v(1-u)}}{v(1-u)} - \lambda \frac{s^{-\beta-1}}{\gamma} \right] \\
 &= s^{-u} \left[\int \sum_{n=0}^{\infty} \frac{(\gamma + qn)(1+n)}{n!(\delta + pn)} \left(\frac{w}{s^\alpha} \right)^n ds \right] \\
 &= s^{-u} \left[c_2 + c_1 s^{v(1-u)} - \lambda \sum_{n=0}^{\infty} \frac{(\gamma)_{qn}}{(\delta)_{pn}} w^n \int s^{-\alpha n - \beta - 1} ds \right] \\
 &= s^{-u} \left[c_2 + c_1 s^{v(1-u)} - \lambda \sum_{n=0}^{\infty} \frac{(\gamma)_{qn} w^n}{(\delta)_{pn}} \frac{s^{-\alpha n - \beta}}{-(\alpha n + \beta)} \right] \\
 &= c_2 s^{-u} + c_1 s^{v(1-u)-u} + \frac{\lambda}{s^u} \sum_{n=0}^{\infty} \frac{(\gamma)_{qn} w^n}{(\delta)_{pn} (\alpha n + \beta)} \frac{1}{s^{\alpha n + \beta}}
 \end{aligned}$$

Taking the Laplace inverse of the last equation, gives

$$\begin{aligned}
 y(x) &= c_2 \frac{x^{u-1}}{\gamma u} + c_1 \frac{x^{u-v(1-u)-1}}{\gamma(u-v(1-u))} + \\
 &L^{-1} \left[\frac{\lambda}{s^u} \sum_{n=0}^{\infty} \frac{(\gamma)_{qn} w^n}{(\delta)_{pn} (\alpha n + \beta)} s^{\alpha n + \beta} \right]
 \end{aligned}$$

Now using Definition (1) (v), we can get the required solution

$$\begin{aligned}
 y(x) &= c_2 \frac{x^{u-1}}{\gamma u} + c_1 \frac{x^{u-v(1-u)-1}}{\gamma(u-v(1-u))} + \\
 &\frac{\lambda}{\gamma u} \int_0^x t^{u-1} (x-t)^{\beta-1} E_{\alpha, \beta+1, p}^{\gamma, \delta, q} w(x-t)^\alpha dt
 \end{aligned}$$

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