## **CHAPTER FIVE**

## CONCLUSION AND RECOMMENDATION

### **5.1** Conclusion

The system will have high response and better characteristics than the classical control, also there is no significant difference between the cost of the PLCs and its accessories compared with the cost of relays and the Automatic Voltage Regulators (AVRs).

The reliable components reduce the maintenance cost and also have a long life time compared with the relays which have moving parts that weaken as a result of increase of the operation frequency then the life time reduced.

The system will not affect by the surrounding environment because the PLC designed to work under bad conditions; like vibrations, temperature and humidity. Hence, these are advantages over the computerize control.

#### **5.2 Recommendations**

After design implementation of the project there are some recommended as follows:

- > Recommended to implementation a project a practically.
- ➤ Recommended to use PLC better specifications contains greater than number entrances and exits.

## Reference

- [1] B.L. Theraga, "Electrical Technology", New Delhi, 1987.
- [2] JJ Di Steffano, IJ Williams "Feedback and control systems", Schaums outline series, McGraw Hill 1967.
- [3] Kuphaldt, Tony R. "Chapter 6 LADDER LOGIC". Lessons in Electric Circuits -- Volume IV.
- [4] Edward W. Kamen, "Industrial Controls and Manufacturing", Academic Press, 1999.
- [5] K.A. GANGADHAR, "Electric Power Systems", Delhi ,1st Reprint, 1999, January
- [6] Gupta, "Performance and Design of Alternating Current Machines", Delhi, Third Edition, 1985
- [7] Hugh Jack, "Automating Manufacturing Systems with PLCs", Version 4.2, April 3, 2003.

## **Appendices Appendix A (simulation)**

```
M80
```

```
M13
                                                                                                            M101
128
                                                                                                           M100
-( )-
       M12
 132
       M15
       M101
```

```
M100
154
      D3 K33000
162
      D3 K33413
      D3 K33825
174
      D3 K34238
180
      D3 K34650
186
      D3 K32588
192
      D3 K32175
                                                                                            M55 )——
     D3 K31763
204
      D3 K31350
210
      D3 K30938
216
```

```
D3 K30113
228
234
      D3 K29288
240
      D3 K28875
246
      D3 K28463
252
      D3 K28050
                                                                                       M65 )
258
     M49
                                                                                      __( Y15 )____
     M50
     M51
     M52
     M53
     M54
     M55
     M56
    M57
```

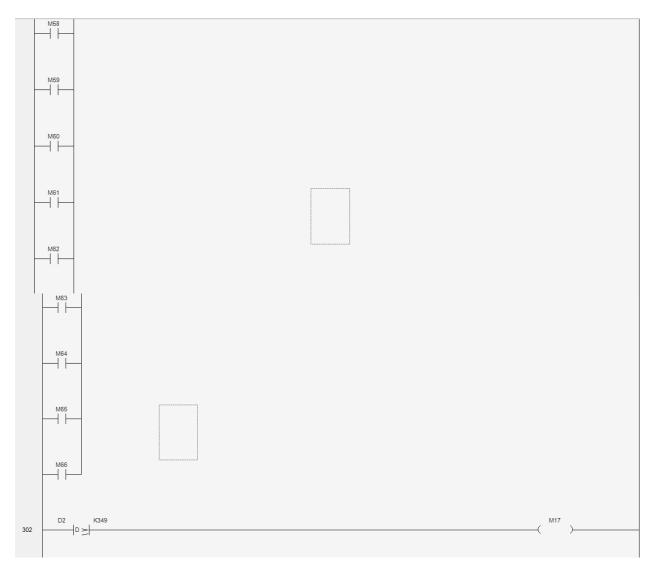
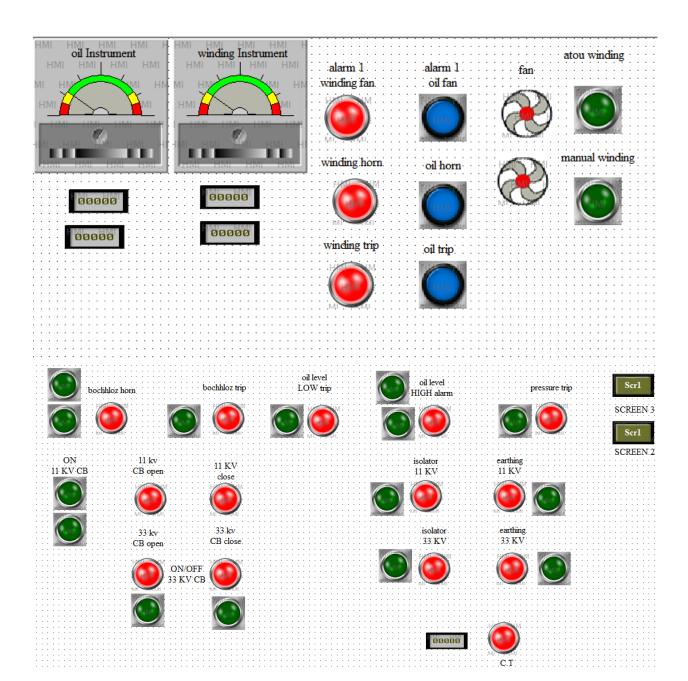


Figure A.1: ladder program of circuit



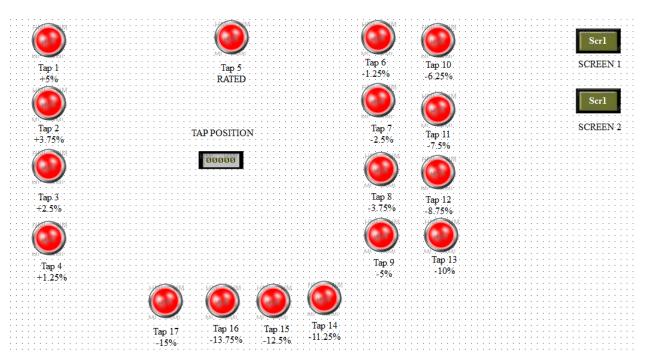


Figure A.2: simulation of circuit

# Appendices Appendix B (contents of transformer)

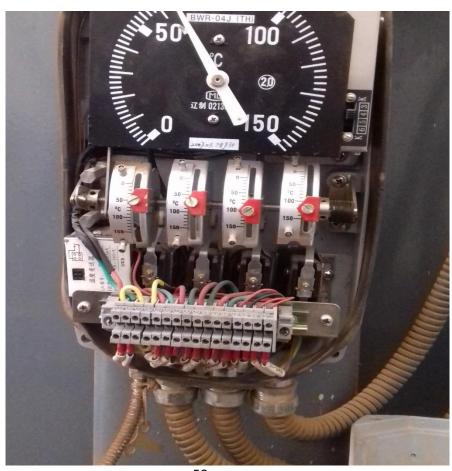


Figure B.1: oil/winding temperature sensor



Figure B.2 : bukhhloz relay



Figure B.3: contactors