

بسم الله الرحمن الرحيم

: قال تعالى

رَبِّ أَوْزِعْنِي أَنْ أَشْكُرَ نِعْمَتَكَ الَّتِي أَنْعَمْتَ
عَلَيَّ وَعَلَىٰ وَالِدَيَّ وَأَنْ أَعْمَلَ صَالِحًا تَرْضَاهُ
وَأَدْخِلْنِي بِرَحْمَتِكَ فِي عِبَادِكَ الصَّالِحِينَ

صدق الله العظيم

(سورة النمل 19)

DEDICATION

This work is sincerely dedicated to:

My Father's Soul

My Mother

My Brothers& Sisters

My Husband

My Family & Friends

And all the loved ones

For all those times you stood by me

For all the joy you brought to my life

For every dream you make come true

For all the love I found in you.....

I'll always be grateful and thankful

I feel blessed because I have you...

I wish you can sense my deepest love an utmost appreciation

ACKNOWLEDGMENT

Firstly I kneel on my knees in affirm faith to **ALLAH** for helping and strengthening me throughout my life gradually till I reached this point.

Then, I would like to express my deep gratitude and thanks to the one who gave me his precious time, his witty suggestions, his utmost care and patience **Dr. AbdElrasoul G. Elzubaidy** who supervised this thesis until it was finally accomplished.

I also would like to thank Eng. Alzahra'a AbdElrahman, Eng. Sharaf Eldin Awad and Eng. Jamal Fathi for their assistance, intense keen and great help.

My greatest thanks to my mother, brothers, sisters and husband who were with me from the very start and were always there to support me at all times of need.

Finally I do thank the Electronics Engineering Department and the College of Graduate Studies at Sudan University of Science & Technology, my family, friends and all those who showed great attention and encourage me to achieve this work.

Abstract

Need for signal processing and filtering are as old as electronic engineering itself, but recent developments in telecommunications, multimedia, and modern warfare have pushed design requirements to before unknown levels. Quest for more bandwidth, better sound definition and better video compression has fuelled significant new developments in filter designs. Starting point for any aspiring electronic engineer is learning to use industry-standard MATLAB software package and exploring its numerous uses in signal processing and filter design.

Here MATLAB is used to design one of the most needed digital filters nowadays, the Moving Average filter the design is built based on characteristic equations and Z-transform.

الخلاصة

ضرورة تنقية ومعالجة الإشارات هي بقدم الهندسة الالكترونية نفسها، ولكن التطورات الأخيرة في الاتصالات السلكية واللاسلكية ، والوسائط المتعددة ، والحروب الحديثة دفعت لشروط التصميم قبل مجهولين. البحث عن المزيد من عرض النطاق الترددي، وأفضل صوت وأفضل تعريف الفيديو غذى ضغط كبير التطورات الجديدة في ترشيح التصاميم. نقطة الانطلاق لأي مهندس يطمح هو التعلم الإلكتروني لاستخدام معايير الصناعة MATLAB واستكشاف حزمة البرامج العديدة يستخدم في تنقية ومعالجة الإشارات وتصميم. هنا MATLAB تستخدم لتصميم واحد من أكثر الأيام تحتاج فلتير رقمي ، والمتوسط المتحرك فلتير تصميم مبني على أساس الخصائص المعادلات وتحويل زد.

Sudan University of Science and Technology
College of Graduate Studies

Moving Average Filter Design Using
MATLAB

تصميم مرشح رقمي متحرك باستخدام الماتلاب

***A thesis submitted in partial fulfillment of the requirements for
the degree of M.Sc in Electronics Engineering (Communication)***

Prepared by:

May Mohammed Elmustafa Hassan

Supervised by:

Dr. AbdElrasoul Jabbar Elzubaidi

September 2009

Table of Contents

الايه

I

Dedication

II

Acknowledgement

III

Abstract

IV

الخلاصة

V

Table of contents

VI

List of tables & figures

IX

Abbreviations & Acronym

Chapter One – Introduction

1-1 Background

1

1-2 Problem Statement

2

1-3 Objectives

2

1-4 Methodology

3

1-5 Thesis Outlines

3

Chapter Two - Digital Filters

2-1 Introduction

4

2-2 Classification by technology

6

2-2-1 Passive filters

6

2-2-2 Single element types

7

2-2-3 L filter

7

2-2-4 T and π filters

7

2-2-5 Multiple element types

8

2-2-6 Active filter

8

VI

2-2-7 Digital Filters

9

2-3 Other filter technologies

9

2-3-1 Quartz filters and piezoelectrics

9

2-3-2 SAW Filters

10

2-3-3 BAW Filters

10

2-3-4 Garent Filters

11

2-3-5 Atomic Filters

11	
2-4	Advantages of Digital Filters
11	
2-5	Operation of Digital Filters
12	
2-6	Order of Digital Filters
13	
2-7	Digital filter coefficients
14	
2-8	Transfer functions
14	
2-9	Types of Digital Filters
15	
2-9-1	Synthesis of IIR Filters
16	
2-9-2	Synthesis of Computationally Efficient FIR Filters
17	
2-10	Filter Response Design Methods
18	
2-11	Moving Average Filter
19	
2-11-1	Frequency Response of a Moving Average Filter:
21	
2-11-2	Recursion and the Moving Average

21 **Chapter Three - Z Transform**

3-1 Introduction

22

3-2 Z Transform

22

VII

3-3 Geophysical Definition

23	
3-4	Inverse Z-transform
24	
3-5	Z-Transform Properties
24	
3-6	Relationship to Laplace
27	
3-7	Relationship to Fourier
27	
3-8	Linear constant-coefficient difference equation
28	
3-9	Transfer function
28	
3-10	Zeros and poles
29	
3-11	Output response

29 **Chapter Four – MATLAB Design Programming**

4-1	Introduction
30	
4-2	Some general features of MATLAB
30	
4-3	The MATLAB System
31	
4-3-1	Development Environment
31	
4-3-2	The MATLAB Mathematical Function Library
31	
4-3-3	The MATLAB Language
31	
4-3-4	Handle Graphics
32	
4-3-5	The MATLAB Application Program Interface (API)
32	

4-4 MATLAB and Digital Filters

32

4-5 M-files

35

4-5-1 Requirements for a function

36

4-5-2 Path

36

4-5-3 Nargin & Nargout

VIII

37

4-5-4 Varargin & Varargout

37

4-5-5 Useful syntax guidelines

38

Chapter Five - Case Study

5-1 Equipment Used

39

5-2 Filters design in MATLAB

39

5-3 Design Procedures

40

5-3-1 The Flow Chart

40

5-3-2 The Code

41

Chapter Six – Results & Discussion

6-1 Results

43

6-2 Discussion

44

Chapter Seven – Conclusion

7-1 Conclusion

45

7-2 Recommendation

IX

List of Tables & Figures

Table 3-1 Properties of the Z Transform	25
Table 5-1 Input Signal Samples	41
Figure 2-1 Filter Block Diagram	5
Figure 2-2 A low-pass electronic filter realized by an RC circuit	7
Figure 2-3 Low-pass π filter	7
Figure 2-4 High-pass T filter	8
Figure 2-5 A general finite impulse response filter	9
Figure 2-6 Moving Average Filter Response a,b,c	20
Figure 2-7 Frequency Response of the Moving Average Filter	21
Figure 4-1 Block Diagram of Filter Elements	32
Figure 4-2 Signal Flow Graph of Filter Elements	33
Figure 4-3 Signal Flow Graph of IIR Filter	34
Figure 4-4 Signal Flow Graph of FIR Filter	34
Figure 5-1 Moving Average Filter Flow Chart	40
Figure 5-2 Moving Average Filter Block Diagram	42
Figure 6-1 Design Output Response	43

X

Chapter One

Introduction

Chapter Two

Digital Filters

Chapter Three

Z Transform

Chapter Four

MATLAB Design

Programming

Chapter Five

Case Study

Chapter SIX

Results & Discussion

Chapter Seven

Conclusion

References

Appendix