

References

- [1] Ogata, Katsuhiko. , "Modern Control Engineering", New Jersey: Prentice Hall, pp 1-3, 1997.
- [2] Ljung, L, "*System Identification-Theory for the user*", Prentice Hall, 1987.
- [3] Friedland, Bernard. , "*Control System design*", New York: McGraw-Hill, pp 30-52, 1987.
- [4] Guez, A., Selinsky,J., "A trainable neuromorphic controller", *Journal of Robotic Systems*", Vol. 5, No.4, pp 363-388, 1988.
- [5] Davalo, Naim," *Neural Networks*", Macmillan, 1991.
- [6] Hunt and Sbarbaro, "Neural Networks for Control System - A Survey", *Automatic*, Vol. 28, pp. 1083-1112, 1992.
- [7] Neural Network Toolbox Users Guide, the Math works Inc, 1998.
- [8] Pham and Liu, "*Neural Networks for Identification*", Prediction and Control, Springer, 1995.
- [9] Cybenko,G, "Approximation by superposition of a Sigmoidal Function, *Mathematics of Control, Signals and Systems*", Vol 2, No. 4, pp 303-314, 1989.
- [10] Saerens M., Soquet A., "Neural Controller based on back-propagation algorithm", *IEE Proceedings –F*, Vol. 138, No.1, pp 55-62, 1991.
- [11] Narendra K.S., Parthasarathy K., "Identification and control of dynamical systems using neural networks", *IEEE Transactions on Neural Networks*", Vol.1,No.1, pp 4-27, 1990.

- [12] Zurada, Jacek M., "Introduction to Artificial Neural System", West Publishing Company, 1992.
- [13] Billings, S.A., "Introduction to nonlinear system analysis and identification", Berlin, 1989.
- [14] Johansson, Rolf -, " *System modeling and identification*", Prentice Hall, 1993.
- [15] Hagan, M and Demuth, H-, " *Neural Network Design* ", Boston, PWS, 1996.
- [16] Marco, P and Raul, L "Application of several neuro control schemes to a 2 DOF manipulator", 1998.
- [17] Magnus Norgaard, *Neural Network Design Toolkit*,
<http://www.iau.dtu.dk/research/control/nlib/manual.pdf>, 07/10/2011
- [18] Barto, Sutton and Anderson, "Neuronlike adaptive elements that can solve difficult learning control problems", *IEEE Trans on Systems, Man and Cybernetics*, Vol. SMC-13, pp 834-846, Sept-Oct 1983.
- [19] C.W. Anderson, " Learning to control an inverted pendulum using neural networks", *IEEE Controls Systems Magazine*, 1989.