الآبية

﴿ لَئِن َ أَلَا تَهُم َّن ْ خَ لَ قَالَ اللَّهِ مَ او وَاللَّلِ أَ وَ صُن َ سَخَّ رَالشَّ مُ سَ الْ قَمَ رَ ال

صدق الله العظيم

سورة العنكبوت : (61)

DEDICATION

At the beginning, I thank ALLAH for giving me the strength and health to let this work see the light. With much pleasure I wish to dedicate this research to my grand mother **Altouma Bashir**, my father **Hassan Ahmed Fedail** and my mother **Afaf Fadl Elmoula**.

Also to my brothers **Haitham**, **Asim**, **AbdElaziem**, and my sisters **Nesrien** and **Nashwa** whom support me to complete this work.

ACKNOWLEDGEMENT

I wish to express my thanks and gratitude to my supervisor **Dr. Abd Alrasoul Jabbar** for his help and guidance through several stage of this research. I am also grateful for the assistance of my colleagues and staff of College of Engineering, School of Electrical and Nuclear Engineering.

ABSTRACT

Solar energy is viewed as clean and renewable source of energy. It is the energy of the future; so the use of Photo Voltaic (PV) systems has increased in many applications. That need to improve the materials and methods used to harness this power source. This thesis includes the design and implementation of a microcontroller-based solar panel tracking system with single degree of freedom. The control circuit for the solar tracker is specifically based on an ATMega16 microcontroller and stepper motor. This is programmed to detect the sunlight through the Light Dependent Resistor (LDR) and then actuate the stepper motor to position the solar panel where it can receive maximum sunlight. The main aim of this thesis is to get maximum power from the sun by solving the problem of system work during bad weather or when the clouds, using a scan technique to detect the position of the sun.

المستخلص

تعتبر الطاقة الشمسية احد المصادر النظيفة والمتجددة للطاقة و تعتبر طاقة المستقبل؛ وهذا ادي الي ازدياد عدد التطبيقات التي تستخدم الواح الخلايا الشمسية. هذا يتطلب تحسين المواد والطرق المستعملة لتسخير مصدر الطاقة هذا.

هذا البحث يحتوي علي تصميم وتنفيذ نظام تتبع لوحة للطاقة الشمسية بالاعتماد علي متحكم دقيق مع درجة واحدة من الحرية. تعتمد دائرة التحكم لتعقب الطاقة الشمسية تحديدا علي متحكم دقيق من نوع AT mega 16 ومحرك خطوة. يتم برمجة المتحكم للكشف عن ضوء الشمس من خلال مقاومة ضوئية متغيرة تتغير مع شدة الضوء ومن ثم اعطاء اشارة لمحرك الخطوة بتحريك الالواح الشمسية حيث يمكن الحصول على اقصى قدر من اشعة الشمس.

الهدف الرئيسي من هذا البحث هو الحصول علي اكبر قدر من الطاقة الشمسية من خلال حل مشكلة عمل النظام اثناء الاحوال الجوية السيئة او عند الغيوم باستخدام تقنية البحث الذاتى للكشف عن موقع الشمس.

TABLE OF CONTENTS

	Page
الاية	I
Dedication	ii
Acknowledgement	iii
Abstract	Iv
المستخلص	V
Table of Contents	
List of Tables	viii
List of Figures	ix
List of Abbreviations	
Chapter One: Introduction	
1.1 Background	2
1.2 Problem Statement	4
1.3 Objectives	4
1.4 Methodology	4
1.5 Research Outline	
Chapter Tow: Solar Tracking System	
2.1 Overview	6
2.2 Literature Review	6
2.3 Renewable Energy	10
2.4 Solar Energy	11
2.5 Electricity from Solar Power	11
2.6 Solar Tracker	12

2.7 Tracking Technique	
2.8 Solar Collector	14
2.8.1 Flat-plate collectors	14
2.8.2 Focusing collectors	14
2.8.3 Passive collectors	15
2.9 Types of Solar Panels	15
2.10 Concentrated Photovoltaic Trackers	17
2.10.1 Single axis trackers	17
2.10.2 Dual axis trackers	18
2.11 Advantage of Solar Tracker	19
2.12 Drive Types	19
2.12.1 Active tracker	19
2.12.2 Passive tracker	20
2.12.2 Passive tracker Chapter Three: Components Description	20
	20
Chapter Three: Components Description	
Chapter Three: Components Description 3.1 Solar Tracker	22
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount	22 23
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount 3.3 Sensors	22 23 23
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount 3.3 Sensors 3.4 Stepper Motor	22 23 23 24
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount 3.3 Sensors 3.4 Stepper Motor 3.5 ULN 2003 Motor Drive	22 23 23 24 26
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount 3.3 Sensors 3.4 Stepper Motor 3.5 ULN 2003 Motor Drive 3.6 AT mega 16 Microcontroller	22 23 23 24 26 27
Chapter Three: Components Description 3.1 Solar Tracker 3.2 Methods of Tracker Mount 3.3 Sensors 3.4 Stepper Motor 3.5 ULN 2003 Motor Drive 3.6 AT mega 16 Microcontroller 3.7 Power Supply	22 23 23 24 26 27 33

Chapter Four: Results and Discussion		
4.1 Schematic Diagram		
4.2 Operation of the Solar Tracking System Using a scan Technique		
4.3 Flow Chart and Main Program		
4.4 Results	41	
4.5 Discussion	42	
Chapter Five: Conclusion and Recommendations		
5.1 Conclusion	46	
5.2 Recommendations		
References		
Appendices		
Appendix A: Main Program		
Appendix B: AT Mega 16 Microcontroller		
Appendix C: Light Dependent Resistor		
Appendix D:ULN 2003	70	
Appendix E:LCD Display		

LIST OF TABLES

Table	Title	Page
3.1	Unipolar stepper motor operation	25
3.2	Port A pins alternate functions	29
4.1	Relationship between modes, range angle and LED	42

LIST OF FIGURES

Figure	Title	
2.1	Principle of solar cells	
2.2	2.2 Principle of photovoltaic cell	
2.3	2.3 Monocrystalline solar panels	
2.4	2.4 Polycrystalline solar panels.	
2.5	2.5 Amorphous solar panels	
2.6	2.6 Single axis tracker	
2.7	Dual axis tracker	18
3.1	Block diagram of the main components	22
3.2	Light dependent resistor	24
3.3	Stepper motor	25
3.4	ULN 2003	26
3.5	Pin diagram of ATmega16	28
3.6	Adapter +9V	33
3.7	Voltage regulator	34
3.8	Voltage regulator circuit	34
3.9	2x16 LCD display	35
3.10	Light emitting diode	35
3.11	The complete circuit design of the sun tracking system	36
4.1	Schematic diagram of the solar system	38
4.2	Flow chart of the main program	40
4.3	Illustrative example 1 (a)	43
4.4	Illustrative example 1 (b)	43
4.5	Illustrative example 2 (a)	44
4.6	Illustrative example 2 (b)	44

LIST OF ABBREVIATIONS

PV	Photo Voltaic
MPP	Maximum Power Point
CSP	Concentrating Solar Power
CPV	Concentrated Photo Voltaic
HSAT	Horizontal Single Axis Tracker
VSAT	Vertical Single Axis Tracker
TSAT	Tilted Single Axis Tracker
PASAT	Polar Aligned Single Axis Tracker
TTDAT	Tip-Tilt Dual Axis Tracker
AADAT	Azimuth -Altitude Dual Axis Tracker
LDR	Light Dependent Resistor
DC	Direct Current
LCD	Liquid Crystal Display
BASCOM	BASic COMpiler